

$$m\ddot{x} + 2\gamma\dot{x} + \kappa x = F \cos \omega t$$

$F = -\kappa x$ ; L'rouv's research:  $F = -\kappa x - 2\gamma\dot{x} + \beta x^3$

$\frac{1}{m}$ :  $\ddot{x} + 2\beta\dot{x} + \omega_0^2 x = f \cos \omega t$ ;

• Free oscillator  $\beta = f = 0$ ;

4 versions of solution

$$x(t) = R \cos(\omega_0 t - \varphi)$$

- Damped oscillator
  - over damped
  - critically damped
  - under damped

Forced oscillator:  $\beta = \phi$ ,  $f \neq \omega$  ?

non resonant forcing  $\omega_0 \neq \omega$

$$x(t) = R \cos(\omega_0 t - \phi) + \frac{f}{\omega_0^2 - \omega^2} \cos \omega t$$

free oscillation

forced

oscillation

Resonant forcing  $\omega = \omega_0$

$$\ddot{x} + \omega_0^2 x = f \cos \omega_0 t;$$

$$x_p(t) = A \cos \omega_0 t + B \sin \omega_0 t;$$

- a solution to homogeneous eqns

$$x_p(t) = A t \cos \omega_0 t + B t \sin \omega_0 t;$$

$$\dot{x}_p(t) = A \cos \omega_0 t + B \sin \omega_0 t - A t \omega_0 \sin \omega_0 t + B t \cos \omega_0 t \cdot \omega_0$$

$$\ddot{x}_p(t) = -\omega_0 A \sin \omega_0 t + B \omega_0 \cos \omega_0 t$$

$$- A t \omega_0^2 \cos \omega_0 t - B \omega_0^2 t \sin \omega_0 t$$

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$$\begin{aligned} & - 2\omega_0 A \sin \omega_0 t + 2B \omega_0 \cos \omega_0 t \\ & - A t \omega_0^2 \cos \omega_0 t - B \omega_0^2 t \sin \omega_0 t \\ & + \omega_0^2 A t \cos \omega_0 t + \omega_0^2 B t \sin \omega_0 t \end{aligned}$$

$$= f \cos \omega_0 t$$

$$(\sin \omega_0 t) [-2\omega_0 - B\omega_0^2] \cdot A$$

$$(\cos \omega_0 t) [2B\omega_0 - f] = 0$$

$$A = 0, B = f / (\omega_0 \cdot 2)$$

$$x(t) = R \cos(\omega_0 t + \varphi) + \frac{f \cdot t}{2\omega_0} \sin \omega_0 t$$

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$$x(t) \int_{t_0}^t \dots dt$$

$F = -kx -$  becomes inercial

$\uparrow$

$$F = -kx + \frac{1}{2}x^2 - \frac{1}{3}x^3 + \dots$$

Full oscillator:

$$\ddot{x} + 2\beta\dot{x} + \omega_0^2 x = f \cos \omega t;$$

Homogeneous:  $\ddot{x}_0 + 2\beta\dot{x}_0 + \omega_0^2 x_0 = 0;$

$$\lambda^2 + 2\beta\lambda + \omega_0^2 = 0$$

$$\lambda_{1,2} = -\beta \pm \sqrt{\beta^2 - \omega_0^2}$$
$$= -\beta \pm i \sqrt{\omega_0^2 - \beta^2}$$

$$x_0(t) = R e^{-\beta t} \cos(\sqrt{\omega_0^2 - \beta^2} t + \varphi)$$

2 free parameters:  $R, \varphi$

$$\ddot{x} + 2\beta\dot{x} + \omega_0^2 x = f \cos \omega t$$

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$$x = A \cos \omega t + B \sin \omega t$$

$$\dot{x} = -A\omega \sin \omega t + B\omega \cos \omega t;$$

$$\ddot{x} = -A\omega^2 \cos \omega t - B\omega^2 \sin \omega t;$$

$$\left. \begin{aligned} & -A\omega^2 \cos \omega t - B\omega^2 \sin \omega t \\ & -2A\beta\omega \sin \omega t + 2\beta B\omega \cos \omega t \\ & + A\omega_0^2 \cos \omega t + B\omega_0^2 \sin \omega t \end{aligned} \right\} \ddot{x} + 2\beta\dot{x}$$

$$= f \cos \omega t + A\omega_0^2 - f$$

$$(\cos \omega t) (-A\omega^2 + 2\beta B\omega + A\omega_0^2 - f) +$$

$$+(\sin \omega t) (-B\omega^2 - 2A\beta\omega + B\omega_0^2) = 0$$

$$() = 0 \Rightarrow 2A\beta\omega = B(\omega_0^2 - \omega^2)$$

$$A = \frac{B}{2\beta\omega} (\omega_0^2 - \omega^2)$$

$$A(-\omega^2 + \omega_0^2) + 2\beta B\omega = f$$

$$-\frac{\beta(\omega_0^2 - \omega^2)}{2\beta\omega} + 2\beta\omega B = f$$

$$\beta \left( 2\beta\omega - \frac{\omega_0^2 - \omega^2}{2\beta\omega} \right) = f$$

$$\beta = \frac{f}{2\beta\omega - \frac{(\omega_0^2 - \omega^2)}{2\beta\omega}} = \frac{2f\beta\omega}{4\beta^2\omega^2 + (\omega^2 - \omega_0^2)}$$

$$A = \frac{f(\omega_0^2 - \omega^2)}{4\beta^2\omega^2 + (\omega^2 - \omega_0^2)}$$



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$$x = A \cos \omega t + B \sin \omega t$$

$$= R \cos(\omega t + \varphi)$$

$$R = \sqrt{A^2 + B^2}; \quad \tan \varphi = B/A$$

$$R = \frac{f}{\sqrt{m^2(\omega_0^2 - \omega^2)^2 + \gamma^2 \omega^2}}$$

$$\tan \varphi = \dots$$

$$A = \frac{f(\omega_0^2 - \omega^2)}{4\beta^2 \omega^2 + (\omega^2 - \omega_0^2)^2}$$

$$B = \frac{2f\beta\omega}{4\beta^2 \omega^2 + (\omega^2 - \omega_0^2)^2}$$

$$R = \sqrt{A^2 + B^2} = \frac{f}{4\beta^2 \omega^2 + (\omega^2 - \omega_0^2)^2}$$

$$\bullet \sqrt{f^2 (\omega_0^2 - \omega^2)^2 + 4f^2 \beta^2 \omega^2}$$

$$= \frac{f}{\sqrt{f^2 (\omega_0^2 - \omega^2)^2 + 4f^2 \beta^2 \omega^2}}$$

$$x(t) = e^{-\beta t} \cos(\omega_0^2 - \beta^2 t - \varphi) + \frac{F \cos(\omega t - \psi)}{\sqrt{F^2(\omega_0^2 - \omega^2)^2 + 4\beta^2 F \omega^2}}$$

$$\tan \varphi = \frac{2\beta\omega}{\omega_0^2 - \omega^2}$$

Method of complex amplification

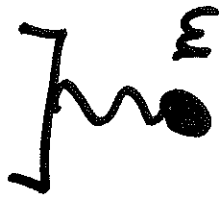
mass.  $5 \text{ kg}$ ,  $\Delta x = 10 \text{ centimeters}$  13

2 Newtons  $4 \text{ cm/sec}$

$$F = 10 \sin\left(\frac{t}{2 \text{ sec}}\right) \text{ Newton}$$

$$v_0 = 3 \text{ cm/sec}, x_0 = 0$$

$$m\ddot{x} + \gamma\dot{x} + kx = F$$



$$F_{\text{spring}} = x \Delta \cdot \gamma$$

$$F = \frac{x \Delta}{\Delta x} = 5 \text{ kg} \cdot 10 \frac{\text{m}}{\text{sec}^2}$$

$$= \frac{10 \text{ cm}}{100}$$

$$= \frac{5 \text{ kg} \cdot 10 \text{ meters}}{\text{sec}^2 \cdot 0.1 \text{ meters}} = 500 \frac{\text{kg}}{\text{sec}^2}$$

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$$F = \gamma \ddot{x} = 2 \text{ Newtons} = \gamma \cdot 4 \text{ cm/sec}^2$$

$$\gamma = \frac{2 \text{ Newtons}}{4 \text{ cm/sec}^2} = \frac{2 \cdot \text{kg} \cdot \text{meters} \cdot \text{sec}^{-2}}{0.04 \text{ meters} \cdot \text{sec}^{-2}}$$

$$= \frac{50 \text{ kg}}{\text{sec}^2}$$

$$5 \text{ kg} \cdot \ddot{x} + \ddot{x} \cdot \frac{50 \text{ kg}}{\text{sec}^2} + 500 \frac{\text{kg}}{\text{sec}^2} \cdot x$$

$$= 10 \sin\left(\frac{t}{2 \text{ sec}}\right) \cdot \text{Newton}$$

$$x(t=0) = 0$$

$$\dot{x}(t=0) = 0.03 \text{ meters/sec}$$

$$[x] = \text{meters}; [\dot{x}] = \frac{\text{meters}}{\text{sec}}; [\ddot{x}] = \frac{\text{meters}}{\text{sec}^2}$$

Change variables

$$X = 1 \text{ meter} \cdot y; \quad t = 1 \text{ sec} \cdot \tau$$

To get

$$5 \text{ kg} \cdot \frac{1 \text{ meter}}{\text{sec}^2} \frac{d^2 y}{d\tau^2} + \frac{50 \text{ kg} \cdot \text{meter}}{\text{sec}^2} \cdot \frac{d y}{d\tau} + 500 \text{ kg} + F \sin \tau$$

$$\text{Newton} = 1 \text{ kg} \cdot \frac{1 \text{ meter}}{\text{sec}^2} \cdot y = 10 \sin(\tau) \cdot \text{Newton}$$

CANCELS

Consider

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$$\ddot{u} + 2\dot{u} + 2u = 5 \sin t$$

$$u(\varphi) = u(\varphi) = 0;$$

Find solution,

does  $\lim_{t \rightarrow \infty} u(t)$

depend upon

initial condition?